

# The Mathematics of Geographic Profiling

Dr. Mike O'Leary

Towson University

Supported by the NIJ through grant 2005-IJ-CX-K036 and 2007-DE-BX-K005

# Project Participants

- Towson University Applied Mathematics Laboratory
  - Undergraduate research projects in applied mathematics.
  - Founded in 1980
- National Institute of Justice
- Special thanks to Iara Infosino (CAA), Stanley Erickson (NIJ), Ron Wilson (NIJ) and Andrew Engel (SAS)

# Collaborators

- Dr. Coy L. May (Towson University) (2005-2006, 2006-2007)
- 2005-2006 Students:
  - Paul Corbitt
  - Brooke Belcher
  - Brandie Bidy
  - Gregory Emerson
  - Laurel Mount
  - Ruozhen Yao
  - Melissa Zimmerman
- 2006-2007 Students:
  - Chris Castillo
  - Adam Fojtik
  - Jonathan Vanderkolk
  - Grant Warble
- 2007-2008 Students:
  - Lauren Amrhine
  - Colleen Carrion
  - Chris Castillo
  - Yu Fu
  - Natasha Gikunju
  - Kristopher Seets

# Geographic Profiling

- **The Question:**

Given a series of linked crimes committed by the same offender, can we make predictions about the anchor point of the offender?

- The anchor point can be a place of residence, a place of work, or some other commonly visited location.

# Geographic Profiling

- What characteristics should a good geographic profiling method possess?
  1. It should be mathematically rigorous.
  2. There should be explicit connections between assumptions on offender behavior and components of the mathematical model.

# Geographic Profiling

- What (other) characteristics should a good geographic profiling technique possess?
  3. It should take into account local geographic features that affect:
    - a. The selection of a crime site;
    - b. The selection of an anchor point.
  4. It should rely only on data available to local law enforcement.
  5. It should return a prioritized search area.

# Main Result

- We have developed a fundamentally new mathematical technique for geographic profiling.
  - We have implemented the algorithm in software, and begun testing it on actual crime series.

# Existing Methods

- Spatial distribution strategies
- Probability distance strategies
- Notation:
  - Anchor point  $\mathbf{z} = (z^{(1)}, z^{(2)})$
  - Crime sites  $\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n$
  - Number of crimes  $n$



# Spatial Distribution Strategies

- Centroid

$$\hat{\mathbf{z}}_{centroid} = \frac{1}{n} \sum_{i=1}^n \mathbf{x}_i$$

- Center of minimum distance;  $\hat{\mathbf{z}}_{cmd}$  minimizes

$$D(\mathbf{y}) = \sum_{i=1}^n d(\mathbf{x}_i, \mathbf{y})$$

- We can use different choices for the metric-  
Euclidean, Manhattan, Travel distance, Travel  
time.

# Spatial Distribution Strategies

- Circle Method (Canter & Larkin, 1993):
  - Anchor point contained in the circle whose diameter are the two crimes that are farthest apart.
  - Offenders who live within the circle are called *marauders*; those who live outside are called *commuters*.

# Probability Distribution Strategies

- The anchor point is located in a region with a high “hit score”.
- The hit score  $S(\mathbf{y})$  has the form

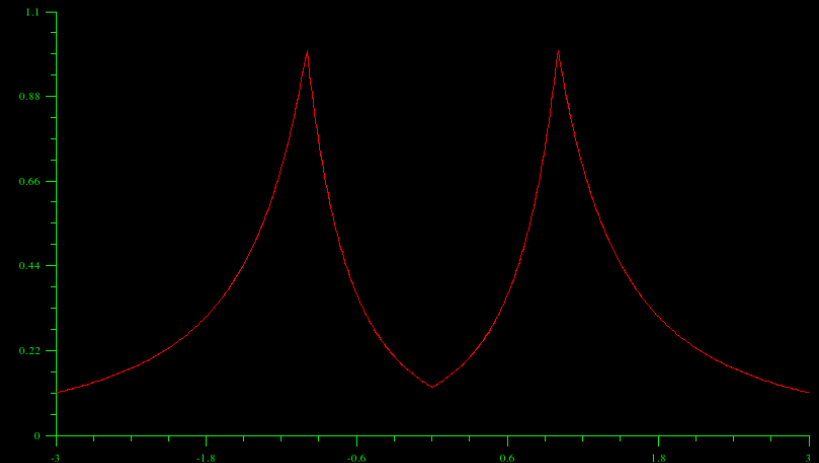
$$\begin{aligned} S(\mathbf{y}) &= \sum_{i=1}^n f(d(\mathbf{y}, \mathbf{x}_i)) \\ &= f(d(\mathbf{z}, \mathbf{x}_1)) + f(d(\mathbf{z}, \mathbf{x}_2)) + \cdots + f(d(\mathbf{z}, \mathbf{x}_n)) \end{aligned}$$

where  $\mathbf{x}_i$  are the crime locations,  $f$  is a decay function and  $d$  is a distance metric.

# Rossmo (Rigel)

- Manhattan distance metric.
- Decay function

$$f(d) = \begin{cases} \frac{k}{d^h} & \text{if } d > B \\ \frac{k B^{g-h}}{(2B-d)^g} & \text{if } d \leq B \end{cases}$$



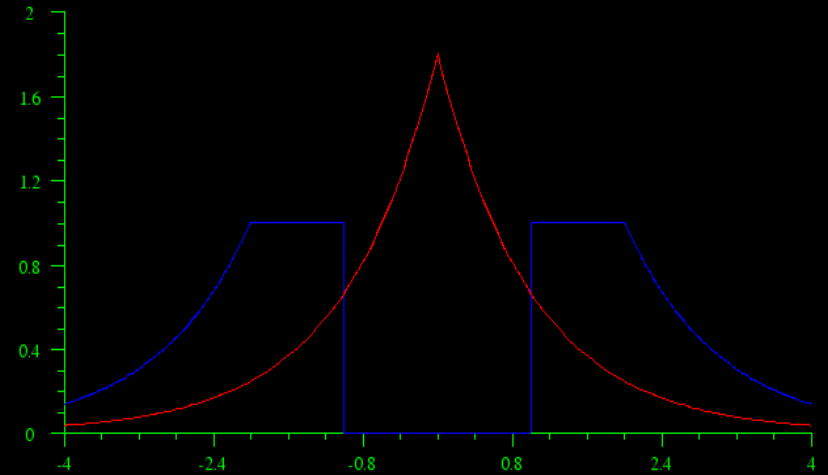
- The constants  $k$ ,  $g$ ,  $h$  and  $B$  are empirically defined.

# Canter, Coffey, Huntley & Missen (Dragnet)

- Euclidean distance
- Decay functions

- $f(d) = A e^{-\beta d}$

- $f(d) = \begin{cases} 0 & \text{if } d < A, \\ 1 & \text{if } A \leq d < B, \\ C e^{-\beta d} & \text{if } d \geq B. \end{cases}$



- Calibrated against homicide data

# Levine (CrimeStat)

- Euclidean distance
- Decay functions

- Linear  $f(d) = A + Bd$

- Negative exponential  $f(d) = A e^{-\beta d}$

- Normal  $f(d) = \frac{A}{\sqrt{2\pi S^2}} \exp\left[\frac{-(d - \bar{d})^2}{2S^2}\right]$

- Lognormal  $f(d) = \frac{A}{d \sqrt{2\pi S^2}} \exp\left[\frac{-(\ln d - \bar{d})^2}{2S^2}\right]$

# CrimeStat

CrimeStat III

**Data setup** | **Spatial description** | **Spatial modeling** | Crime travel demand | Options

Interpolation | Space-time analysis | Journey-to-Crime

Calibrate Journey-to-crime function

Select data file for calibration | Select output file | Select kernel parameters | Calibrate!

Journey-to-crime estimation (Jtc) Incident file: Primary Save output to...

Use already-calibrated distance function

Use mathematical formula

Distribution: Negative exponential

Coefficient: 1.89 Exponent: -0.06

Unit: Miles

Draw crime trips Select data file

Compute Quit

Select data

Files: <None> | Select Files | Edit | Remove

C:\Documents and Settings\moleary\My Documents\CrimeStat\

Origin coordinates

	File	Column	Missing values
X	C:\Documents and Settings\moleary\My Docu	<None>	<Blank>
Y	C:\Documents and Settings\moleary\My Docu	<None>	<Blank>

Destination coordinates

	File	Column	Missing values
X	C:\Documents and Settings\moleary\My Docur	<None>	<Blank>
Y	C:\Documents and Settings\moleary\My Docur	<None>	<Blank>

Type of coordinate system

Longitude, latitude (spherical)

Projected (Euclidean)

Directions (angles)

Data units

Decimal Degrees  Miles

Feet  Kilometers

Meters  Nautical miles

OK

# Probability Distribution Strategies

- Existing methods differ in their choices of
  - The distance measure, and
  - The distance decay function;

but share the common mathematical heritage:

$$S(\mathbf{y}) = \sum_{i=1}^n f(d(\mathbf{y}, \mathbf{x}_i))$$

- In practice,  $S(\mathbf{y})$  may be evaluated only at discrete values  $\mathbf{y}_j$  giving us a hit score matrix

$$S_{ij} = \sum_{i=1}^n f(d(\mathbf{y}_j, \mathbf{x}_i))$$

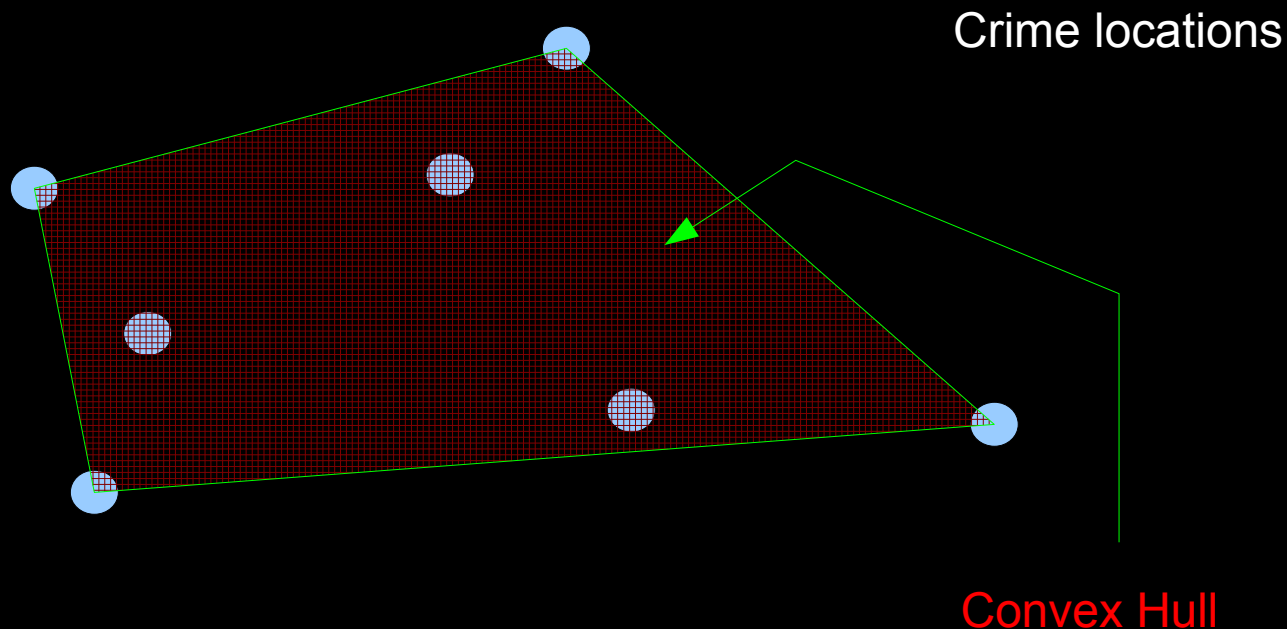


# Shortcomings

- These techniques are all *ad hoc*.
- What is their theoretical justification?
  - What assumptions are being made about criminal behavior?
  - What mathematical assumptions are being made?
- How do you choose one method over another?

# Shortcomings

- The convex hull effect:
  - The anchor point always occurs inside the convex hull of the crime locations.



# Shortcomings

- How do you add in local information?
  - How could you incorporate socio-economic variables into the model?
    - Snook, *Individual differences in distance travelled by serial burglars*
    - Malczewski, Poetz & Iannuzzi, *Spatial analysis of residential burglaries in London, Ontario*
    - Bernasco & Nieuwbeerta, *How do residential burglars select target areas?*
    - Osborn & Tseloni, *The distribution of household property crimes*

# Shortcomings

- These methods require some *a priori* knowledge of the offender's distance decay function.
  - In particular, they require an estimate of the distance that the serial offender is likely to travel before the analysis process begins.
  - Indeed, the constant(s) that appear in the distance decay function must be selected before starting the analysis.

# A New Approach

- Let us start with a model of offender behavior.
  - In particular, let us begin with the ansatz that an offender with anchor point  $\mathbf{z}$  commits a crime at the location  $\mathbf{x}$  according to a probability density function  $P(\mathbf{x} | \mathbf{z})$ .
  - This is an inherently continuous model.

# A New Approach

- Assumptions about
    - The offender's likely behavior, and
    - The local geography
- can then be incorporated into the form of  $P(\mathbf{x} | \mathbf{z})$ .

# The Mathematics

- Given crimes located at  $\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n$  the *maximum likelihood estimate* for the anchor point  $\hat{\mathbf{z}}_{mle}$  is the value of  $\mathbf{y}$  that maximizes

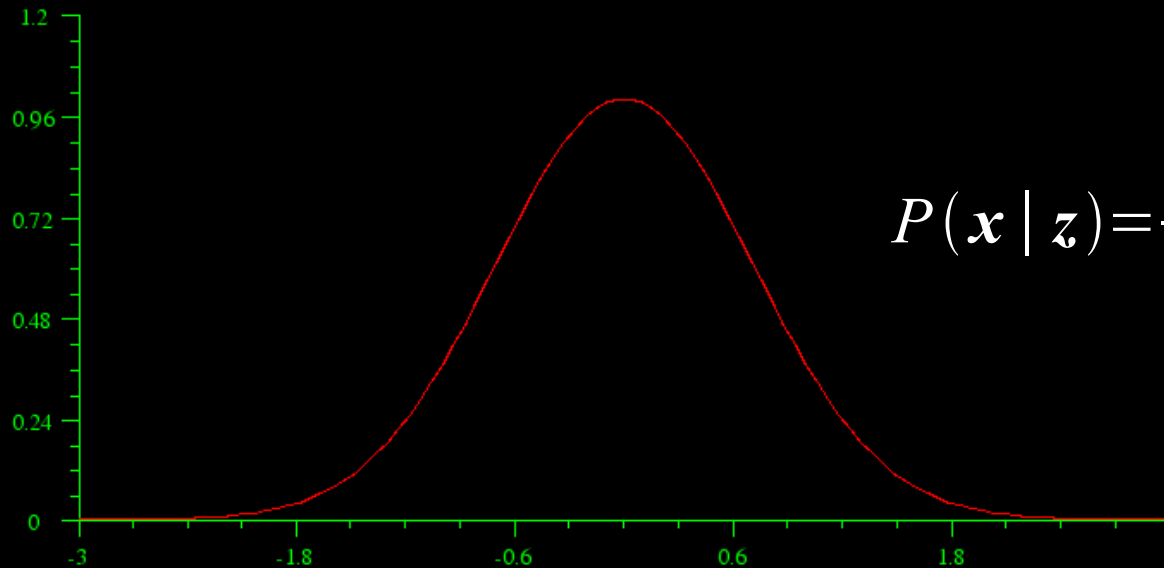
$$\begin{aligned} L(\mathbf{y}) &= \prod_{i=1}^n P(\mathbf{x}_i | \mathbf{y}) \\ &= P(\mathbf{x}_1 | \mathbf{y}) P(\mathbf{x}_2 | \mathbf{y}) \cdots P(\mathbf{x}_n | \mathbf{y}) \end{aligned}$$

or equivalently, the value that maximizes

$$\begin{aligned} \lambda(\mathbf{y}) &= \sum_{i=1}^n \ln P(\mathbf{x}_i | \mathbf{y}) \\ &= \ln P(\mathbf{x}_1 | \mathbf{y}) + \ln P(\mathbf{x}_2 | \mathbf{y}) + \cdots + \ln P(\mathbf{x}_n | \mathbf{y}) \end{aligned}$$

# Relation to Spatial Distribution Strategies

- If we assume offenders choose target locations based only on a distance decay function in bivariate normal form:



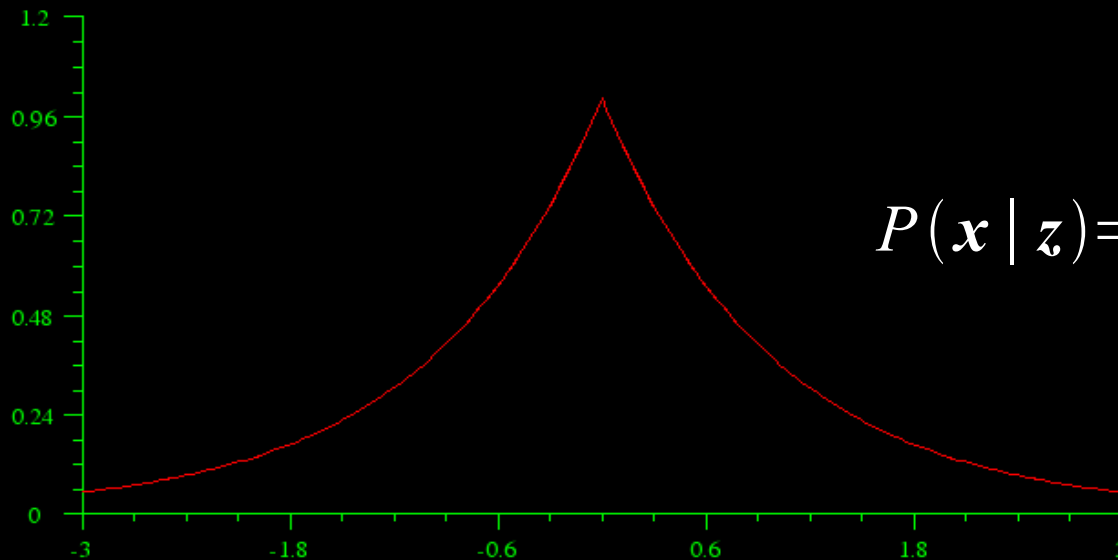
$$P(\mathbf{x} | \mathbf{z}) = \frac{1}{2\pi\sigma^2} \exp\left[-\frac{|\mathbf{x} - \mathbf{z}|^2}{2\sigma^2}\right]$$

- Then the maximum likelihood estimate for the anchor point is the centroid.



# Relation to Spatial Distribution Strategies

- If we assume offenders choose target locations based only on a distance decay function in exponentially decaying form:



$$P(\mathbf{x} | \mathbf{z}) = \frac{1}{2\pi\sigma^2} \exp\left[-\frac{|\mathbf{x} - \mathbf{z}|}{\sigma}\right]$$

- Then the maximum likelihood estimate is the center of minimum distance.

# Relation to Probability Distance Strategies

- What is the log likelihood function?

$$\lambda(\mathbf{y}) = \sum_{i=1}^n \left[ -\ln(2\pi\sigma^2) - \frac{|\mathbf{x}_i - \mathbf{y}|}{\sigma} \right]$$

- This is the hit score  $\mathcal{S}(\mathbf{y})$  provided we use Euclidean distance and the linear decay  $f(d) = A + Bd$  for

$$A = -\ln(2\pi\sigma^2)$$

$$B = -1/\sigma$$

# Parameters

- The maximum likelihood technique does not require *a priori* estimates for parameters other than the anchor point.

$$P(\mathbf{x} | \mathbf{z}, \sigma) = \frac{1}{2\pi\sigma^2} \exp\left[-\frac{|\mathbf{x} - \mathbf{z}|^2}{2\sigma^2}\right]$$

The same process that determines the best choice of  $\sigma$  also determines the best choice of  $\mathbf{z}$ .

# Better Models

- We have recaptured the results of existing techniques by choosing  $P(\mathbf{x} | \mathbf{z})$  appropriately.
- These choices of  $P(\mathbf{x} | \mathbf{z})$  are not very realistic.
  - Space is homogeneous and crimes are equi-distributed.
  - Space is infinite.
  - Decay functions were chosen arbitrarily.

# Better Models

- Our framework allows for better choices of  $P(\mathbf{x} | \mathbf{z})$
- Consider

$$P(\mathbf{x} | \mathbf{z}) = D(d(\mathbf{x}, \mathbf{z})) \cdot G(\mathbf{x}) \cdot N(\mathbf{z})$$

Distance Decay  
(Dispersion Kernel)



Geographic  
factors

Normalization

# Geography

- What geographic factors should be included in the model?
  - Snook, *Individual differences in distance travelled by serial burglars*
  - Malczewski, Poetz & Iannuzzi, *Spatial analysis of residential burglaries in London, Ontario*
  - Bernasco & Nieuwbeerta, *How do residential burglars select target areas?*
  - Osborn & Tseloni, *The distribution of household property crimes*

# Geography

- This approach has some problems.
  - Different crimes have different etiologies.
    - We would need to study each different crime type.
  - There are regional differences.
    - Tseloni, Wittebrood, Farrell and Pease (2004) noted that increased household affluence indicated higher burglary rates in Britain, and indicated lower burglary rates in the U.S.

# Geography

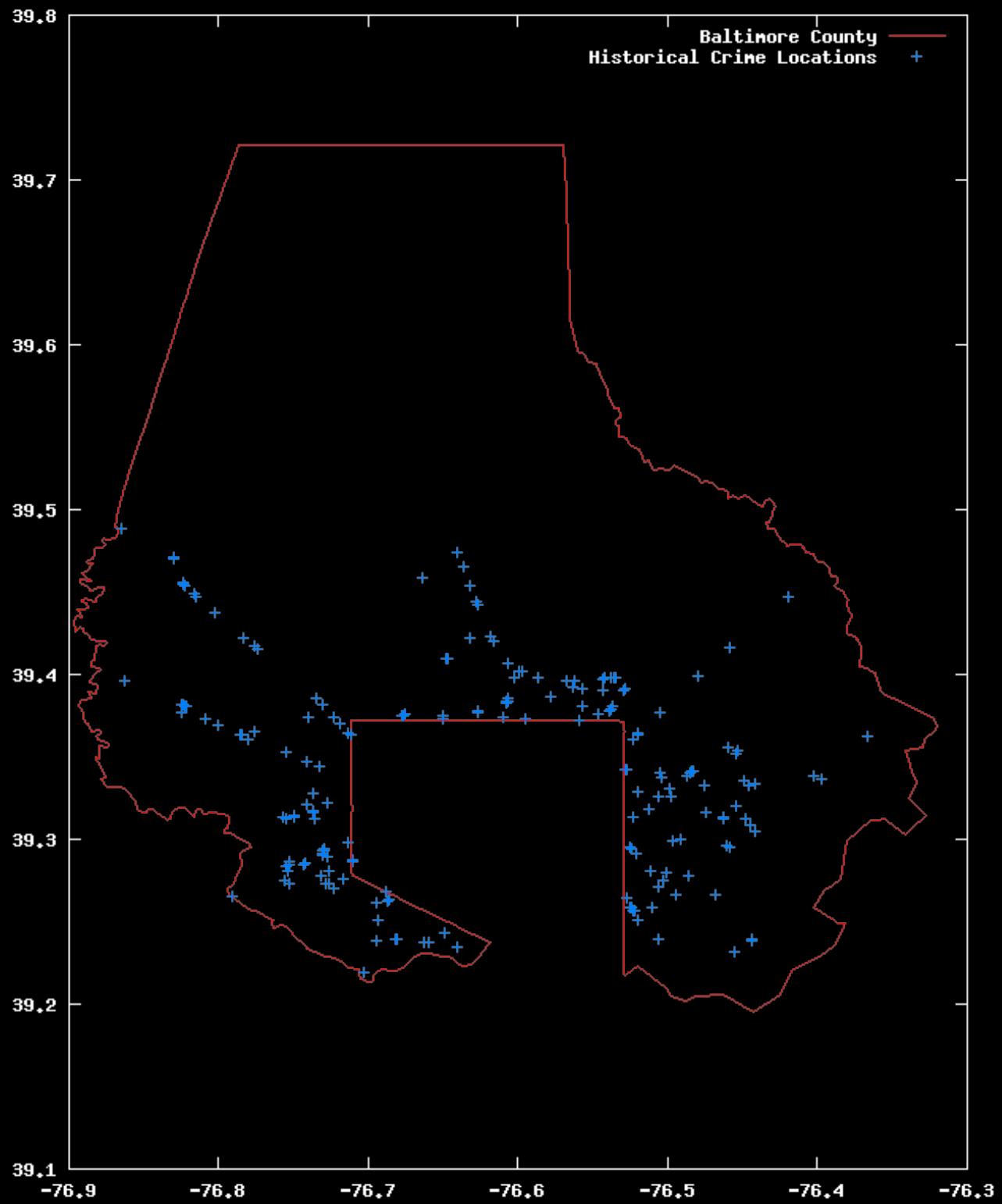
- Instead, we assume that historical crime rates are reasonable predictors of the likelihood that a particular region will be the site of an offense.
  - Rather than explain crime rates in terms of underlying geographic variables, we simply measure the resulting geographic variability.
- Let  $G(x)$  represent the local attractiveness of potential targets.



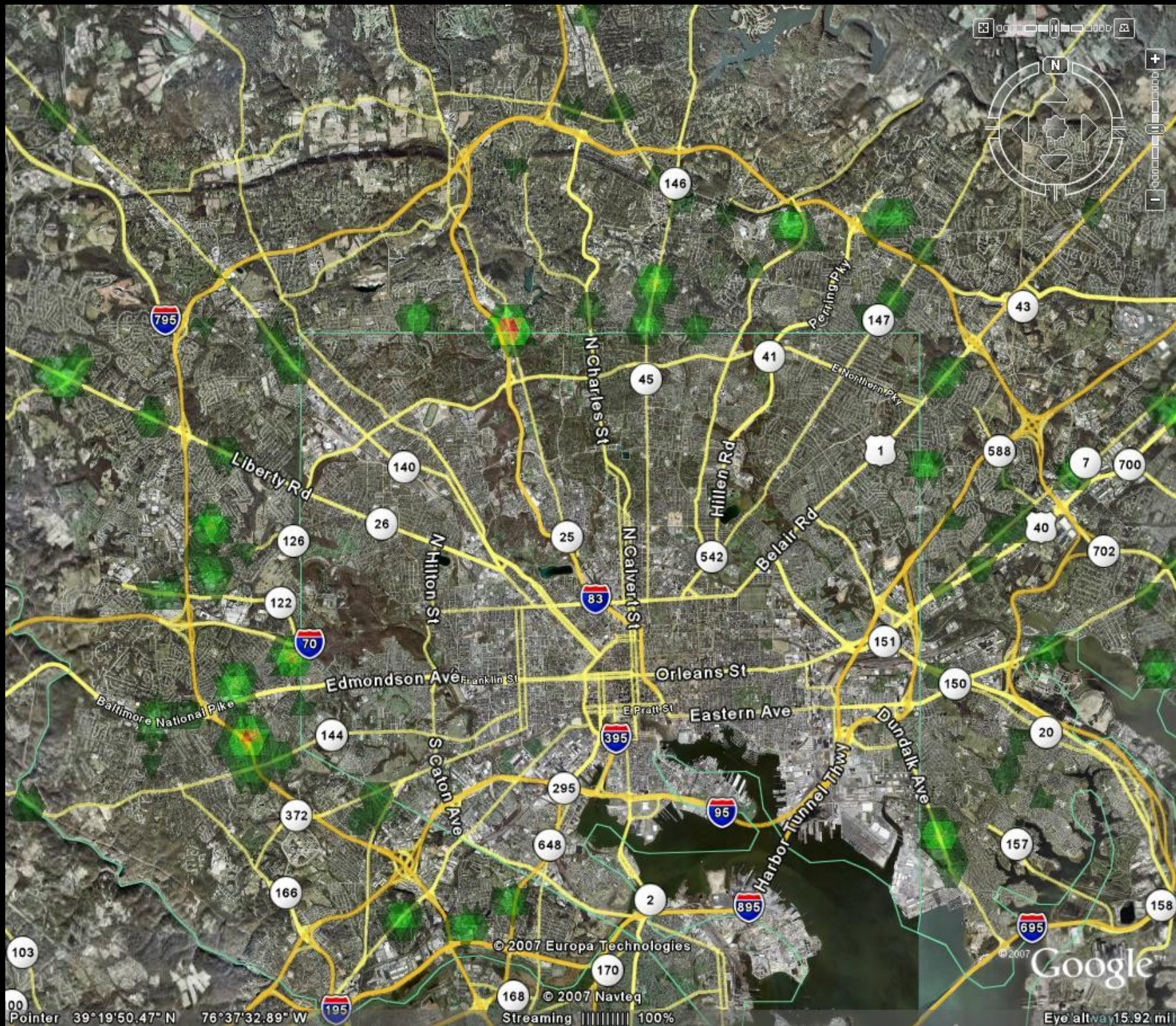
# Geography

- An analyst can determine what historical data should be used to generate the geographic target density function.
  - Different crime types will necessarily generate different functions  $G(x)$ .
- $G(x)$  is calculated by kernel density parameter estimation.

$$G(x) = \sum_{i=1}^N K(x - y_i)$$







Pointer 39°19'50.47" N 76°37'32.89" W

© 2007 Europa Technologies

© 2007 Navteq

Streaming 100%

Google

Eye alt 15.92 mi



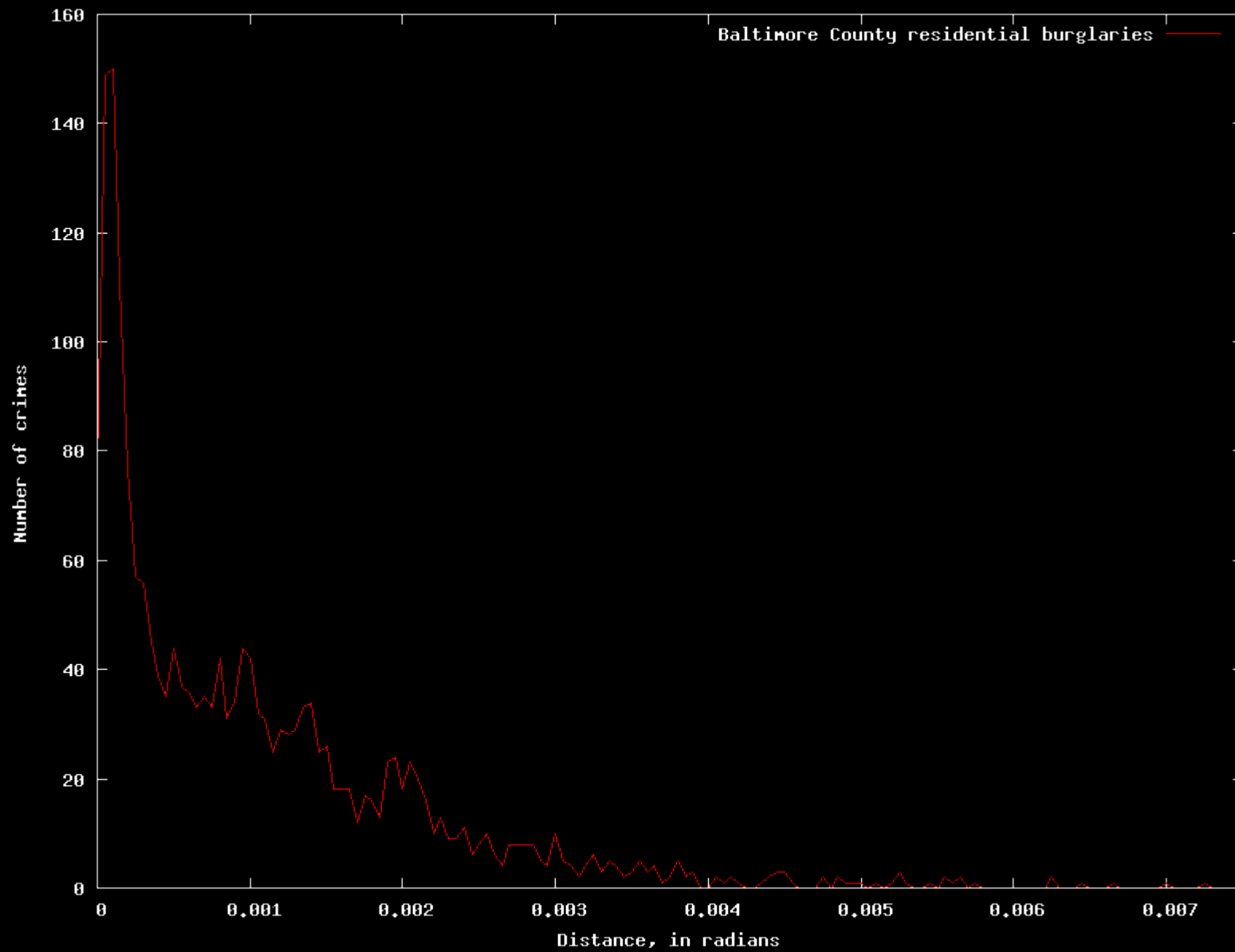
# Geography

- The target attractiveness function  $G(x)$  must also account for jurisdictional boundaries.
  - Suppose that a law enforcement agency gets reports for all crimes within the region  $J$ , and none from outside  $J$ .
  - Then we must have

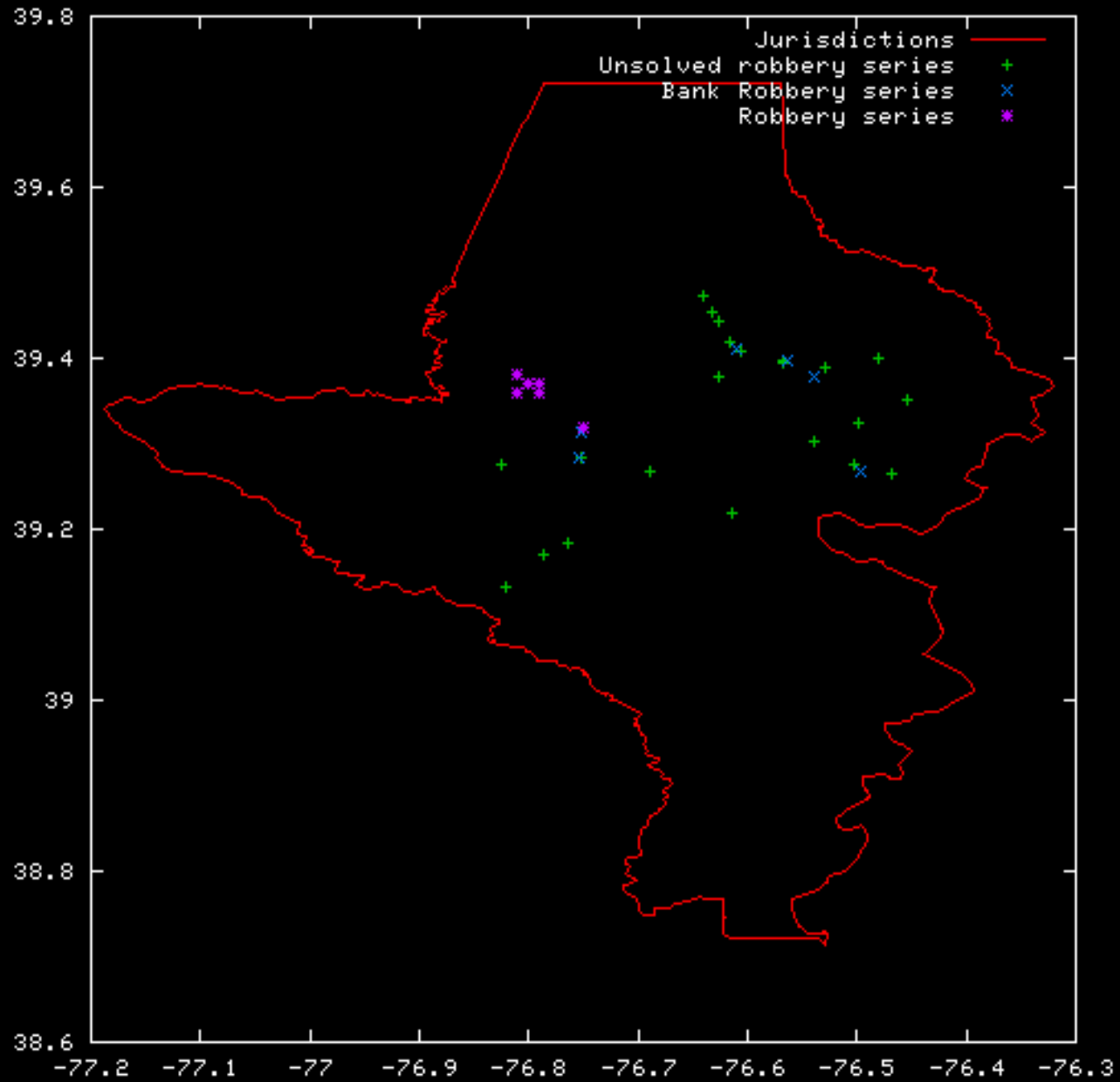
$$G(x) = 0 \quad \text{for all } x \notin J$$

as no crimes that occur outside  $J$  will be known to that agency.

# Distance Decay



# Distance Decay



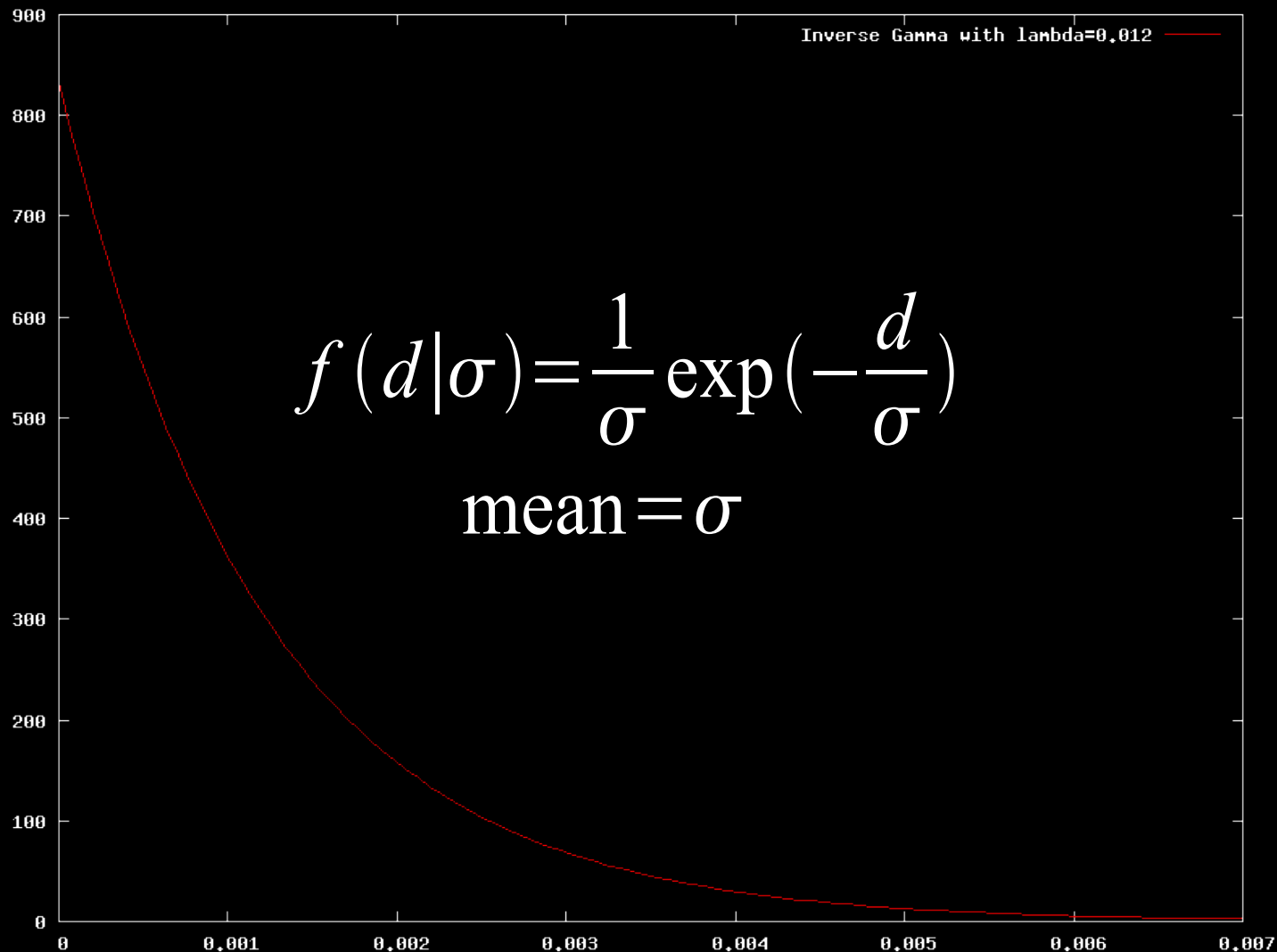
# Distance Decay

- Suppose that each offender has a decay function  $f(d|\sigma)$  where  $\sigma \in \Sigma$  varies among offenders according to the distribution  $\pi(\sigma)$ .
- Then if we look at the decay function for all offenders, we obtain the aggregate distribution

$$F(d) = \int_{\Sigma} f(d|\sigma) \cdot \pi(\sigma) d\sigma$$

# Distance Decay

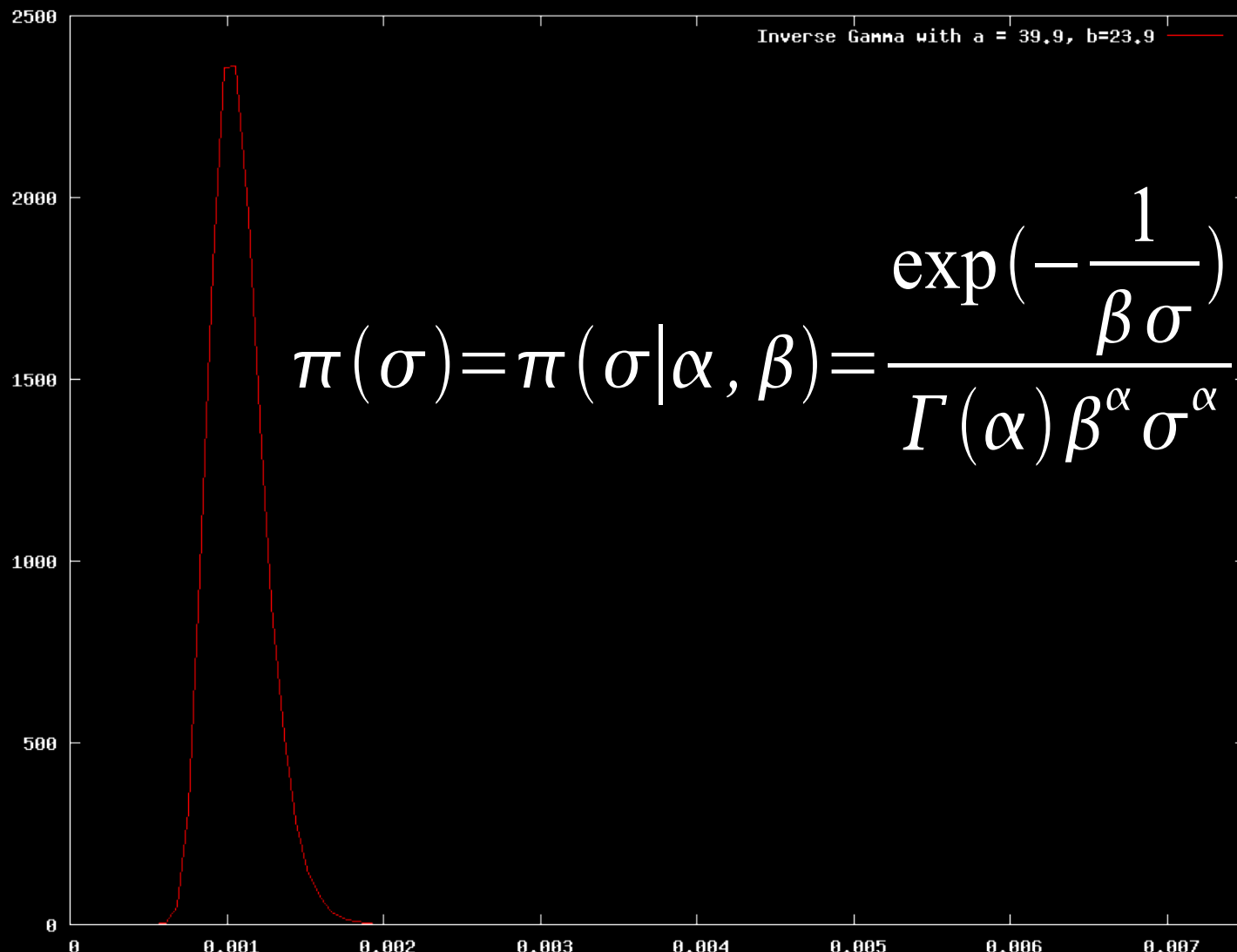
- Suppose that the distance decay behavior of an individual offender is exponentially decaying, so that





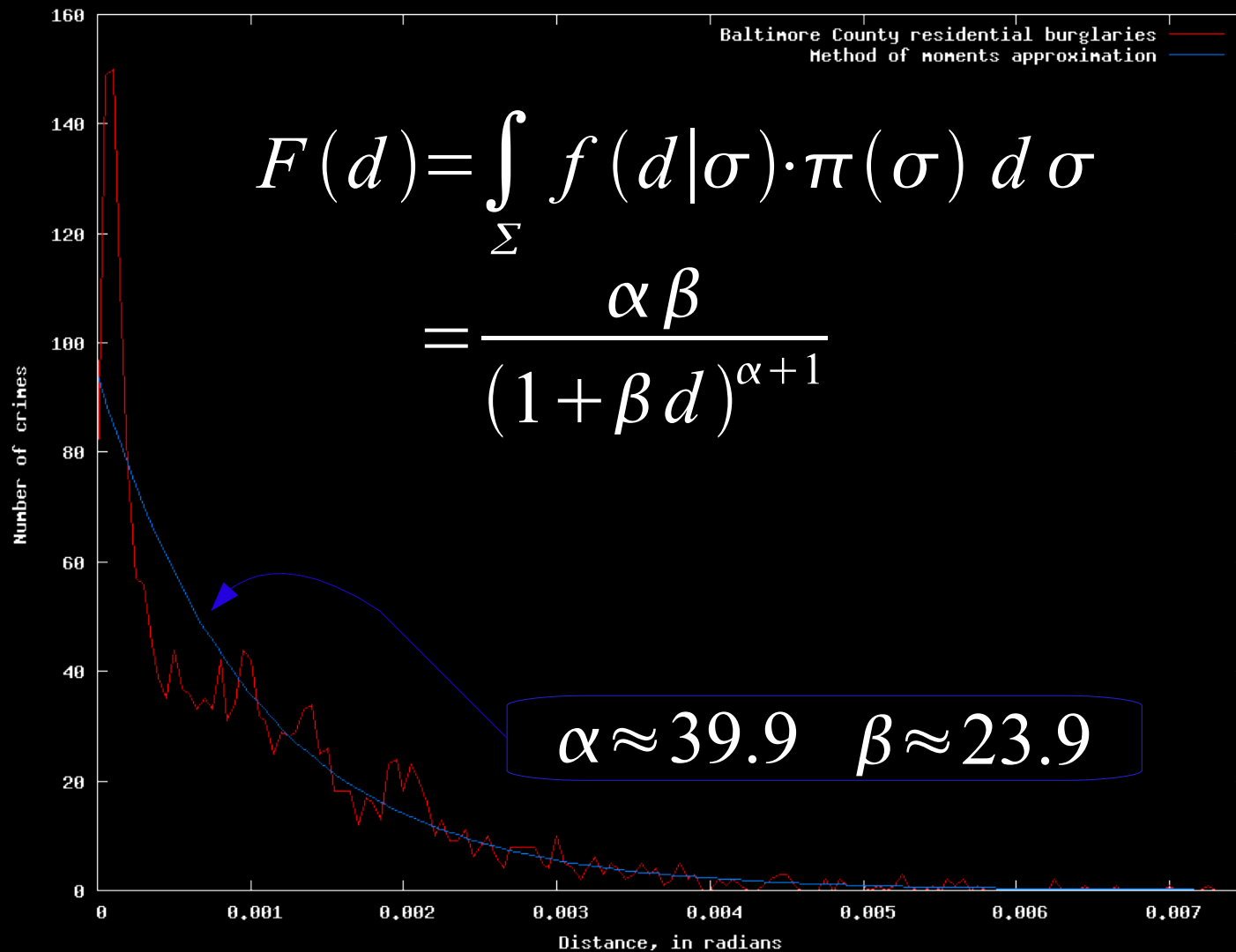
# Distance Decay

- Suppose that the mean distance an offender travels follows an inverse gamma distribution



# Distance Decay

- Then we can equate the first and second moments of the mixture distribution with the empirical data.



# Distance Decay

- This gives us a statistical method to estimate the distribution  $\pi(\sigma)$ .
  - Note that information about  $\pi(\sigma)$  is equivalent to prior information about the offender before the characteristics of the crime series are considered.

# Distance Decay

- We can also try to estimate  $\pi(\sigma)$  by solving for  $\pi(\sigma)$  in

$$F(d) = \int_0^{\infty} \frac{1}{\sigma} e^{-d/\sigma} \pi(\sigma) d\sigma$$

- If  $\pi(\sigma)$  is bounded, then  $F(d)$  is differentiable as

$$|F^{(k)}(d)| \leq \int_0^{\infty} \frac{1}{\sigma^{k+1}} e^{-d/\sigma} \|\pi\|_{\infty} d\sigma \leq \frac{\Gamma(k) \|\pi\|_{\infty}}{d^k}$$

so the map  $\pi \rightarrow F$  is regularizing, (in fact, it is essentially a Laplace transform) so the problem of determining  $\pi(\sigma)$  from  $F(d)$  is unstable.

# Normalization

- The expression

$$P(\mathbf{x} | \mathbf{z}) = D(d(\mathbf{x}, \mathbf{z})) \cdot G(\mathbf{x}) \cdot N(\mathbf{z})$$

is to represent a probability density function; as a consequence,

$$N(\mathbf{z}) = \frac{1}{\iint_J G(\mathbf{y}) D(d(\mathbf{y}, \mathbf{z})) dy^{(1)} dy^{(2)}}$$

# Maximum Likelihood Estimation

- We are then left with the of finding the maximum value of the likelihood function

$$L(y) = \frac{\prod_{i=1}^n D(d(x_i, y)) G(x_i)}{\left[ \iint_J D(d(\xi, y)) G(\xi) d\xi^{(1)} d\xi^{(2)} \right]^n}$$

# Implementation

- We have implemented this algorithm in software.
  - Integration was performed using a seven-point fifth-order Gaussian method.
  - Optimization was performed using a cyclic coordinate technique with a Hooke and Jeeves accelerator.
  - Running time with  $\sim 650$  boundary vertices and  $\sim 1000$  historical crimes is  $\sim 10$  minutes.

Command Prompt

C:\Documents and Settings\mleary\Desktop\v 0.12 devel\Profiler\release>Profiler.exe

Profiler  
Version 0.12 (Pre-Release)

Using Default Parameter file: .\Parameters\Parameters.txt  
 Using Geography file: .\Parameters\baltimore\_county.txt  
 Using Crime Series file: .\Parameters\BCData\Crimes.txt  
 Using Historical data file: .\Parameters\BCData\History.txt  
 Using Output file: .\Parameters\BCData\Likelihood.kml

Triangulating region  
 Setting up target density  
 Calculating mean nearest neighbor distance  
 Precomputing target density  
 Constructing Likelihood Function  
 Constructing Initial Guess  
 Initial spatial guess = ( -76.731598 , 39.311223 )  
 Initial sigma guess = 44.217570

Approximations to anchor point and sigma

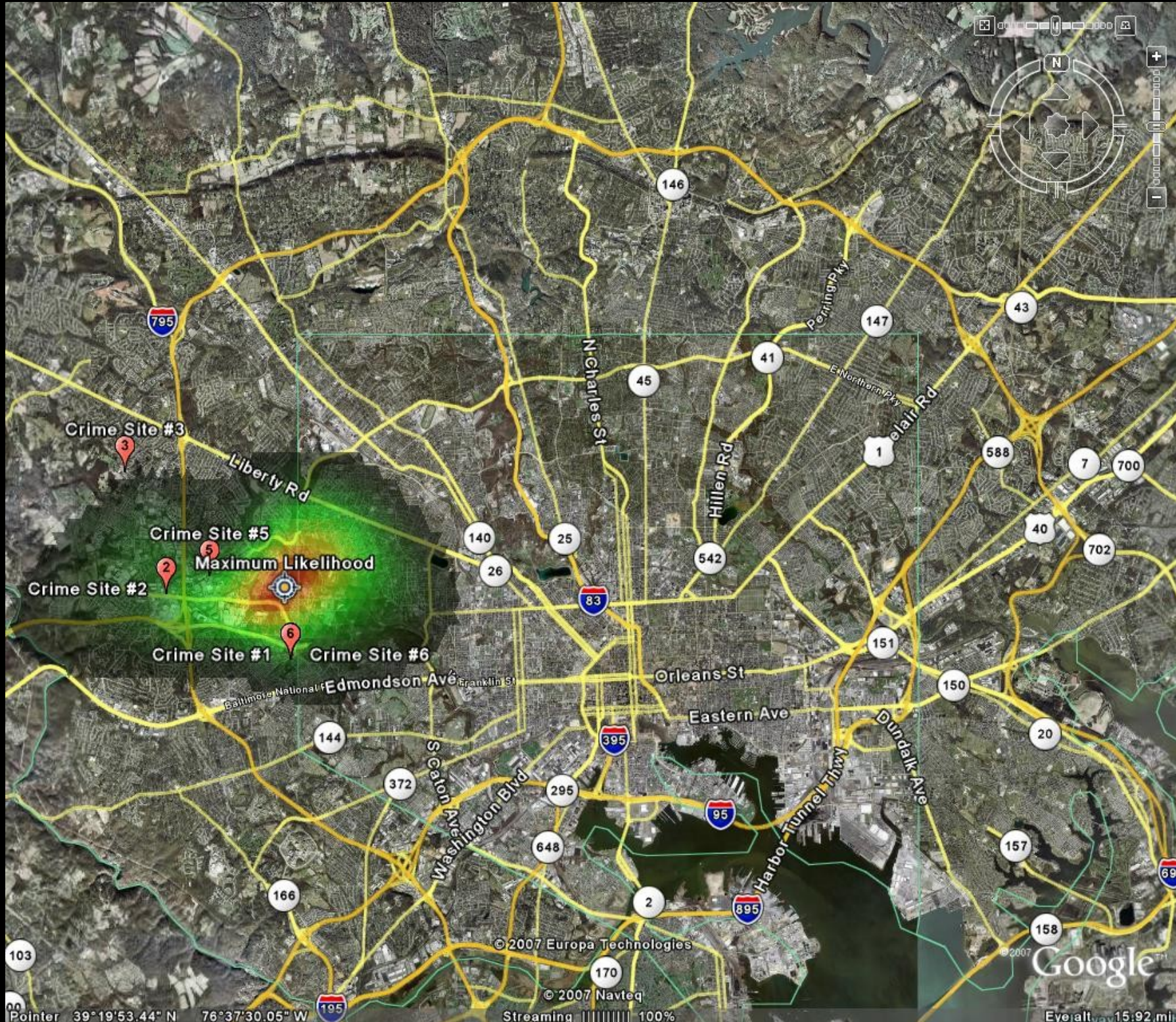
i	x	y	sigma	Likelihood
0	-76.731598	39.311223	44.217570	1.892049e+023
1	-76.716733	39.312793	71.545719	3.909148e+023
2	-76.716733	39.314912	73.128008	4.040361e+023
3	-76.715180	39.314912	72.770779	4.052184e+023
4	-76.715180	39.314912	72.770779	4.052184e+023

-----  
 Estimate of anchor point = ( -76.715180 , 39.314912 )  
 Estimate of sigma = 72.770779  
 -----

Writing KML file for likelihood function

C:\Documents and Settings\mleary\Desktop\v 0.12 devel\Profiler\release>\_







# Likelihood Functions

- The estimate for the maximum likelihood is mathematically rigorous.
- The contour surface shows the likelihood function for the optimal choice of  $\sigma$ .
  - This gives a probability surface for the offender's anchor point *only* if
    - the estimate for sigma is correct, and
    - all anchor points are equally likely.

# Bayesian Methods

- Police agencies would prefer a search area to the point estimate  $\hat{z}_{\text{mle}}$ .
- We take a Bayesian approach.
- If we have one crime

$$\begin{aligned} P(z, \sigma | x) &= \frac{P(x, z, \sigma)}{P(x)} \\ &= \frac{P(x|z, \sigma) H(z) \pi(\sigma)}{\int_{\zeta \in \Sigma} \int_{\zeta \in J} P(x|z, \zeta) H(\zeta) \pi(\zeta) d\zeta d\zeta} \end{aligned}$$

where  $H(z)$  is the prior distribution for anchor points.

# Bayesian Methods

- To calculate the prior distribution of anchor points, we suppose that they are proportional to the local population density, and use block level census data.
  - Choose a kernel functions  $K(x|\lambda)$  with bandwidth  $\lambda$ .
  - Let block  $i$  have center  $y_i$ , population  $P_i$  and area  $A_i$ , and set  $\lambda_i = C \sqrt{A_i}$  for some constant  $C$ .
  - Then

$$H(z) = \sum_{i \in I} P_i K(z - y_i | \lambda_i)$$

# Bayesian Methods

- If we have  $n$  crimes, and we assume that the crime locations are all independent then

$$P(z, \sigma | x_1, x_2, \dots, x_n) \\ = \frac{\prod_{i=1}^n P(x_i | z, \sigma) H(z) \pi(\sigma)}{\int_{\zeta \in \Sigma} \int_{\varsigma \in J} \prod_{i=1}^n P(x_i | \zeta, \varsigma) H(\zeta) \pi(\sigma) d\zeta d\varsigma}$$

# Bayesian Methods

- Since the relevant distribution is the marginal distribution for  $z$ , we easily see that

$$\begin{aligned} P(z|x_1, x_2, \dots, x_n) & \\ & \propto \int_{\sigma \in \Sigma} \prod_{i=1}^n P(x_i|z, \sigma) H(z) \pi(\sigma) d\sigma \\ & \propto \int_{\sigma \in \Sigma} \prod_{i=1}^n D(d(x_i, z), \sigma) G(x_i) \\ & \quad \cdot N(z) H(z) \pi(\sigma) d\sigma \end{aligned}$$

# Strengths of this Framework

- All of the assumptions on criminal behavior are made in the open.
  - They can be challenged, tested, discussed and compared.

# Weaknesses of this Framework

- GIGO
  - The method is only as accurate as the accuracy of the choice of  $P(\mathbf{x} | \mathbf{z})$ .
- It is unclear what the right choice is for  $P(\mathbf{x} | \mathbf{z})$ 
  - Even with the simplifying assumption that

$$P(\mathbf{x} | \mathbf{z}) = D(d(\mathbf{x}, \mathbf{z})) \cdot G(\mathbf{x}) \cdot N(z)$$

this is difficult.



# Weaknesses

- The framework assumes that crime sites are independent, identically distributed random variables.
  - This is probably false in general!
- This should be a solvable problem though...

# Next Steps

- Model improvements:
  - What would a better choice for the model of criminal behavior?
- Model selection and multi-model inference.

# Questions?

Contact information:

Dr. Mike O'Leary

Director, Center for Applied Information  
Technology

Towson University

Towson, MD 21252

410-704-7457

[moleary@towson.edu](mailto:moleary@towson.edu)